

# Structured AI Methods for Real-Time Autonomy in Mobile Robot Systems

## BIOGRAPHY

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## ABSTRACT

Structured AI aims to fuse the benefits of classical, analytical techniques with modern-day machine learning approaches by extracting and incorporating the embedded structures in the operating environments. To do so, it draws inspiration from various fields, such as system dynamics, geometry and topology, cognition, and information theory. In this seminar, I will present some of the recent efforts in this direction to augment the visual perception and information gathering capabilities of autonomous mobile ground robots. Extensive evaluations show enhanced generalization capabilities in cluttered and confined indoor spaces, while reducing computational efforts and (training) data requirements.